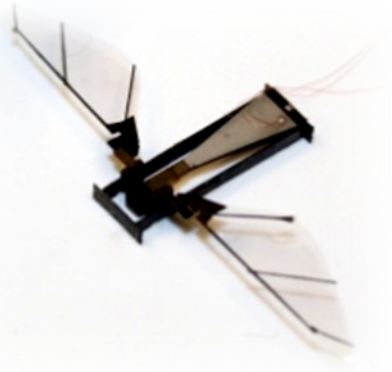
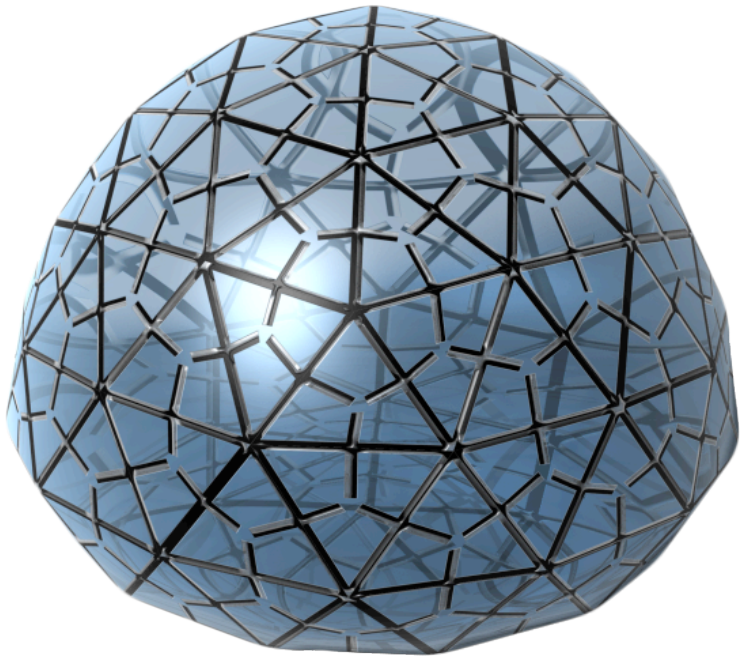


What happens if you step on one?

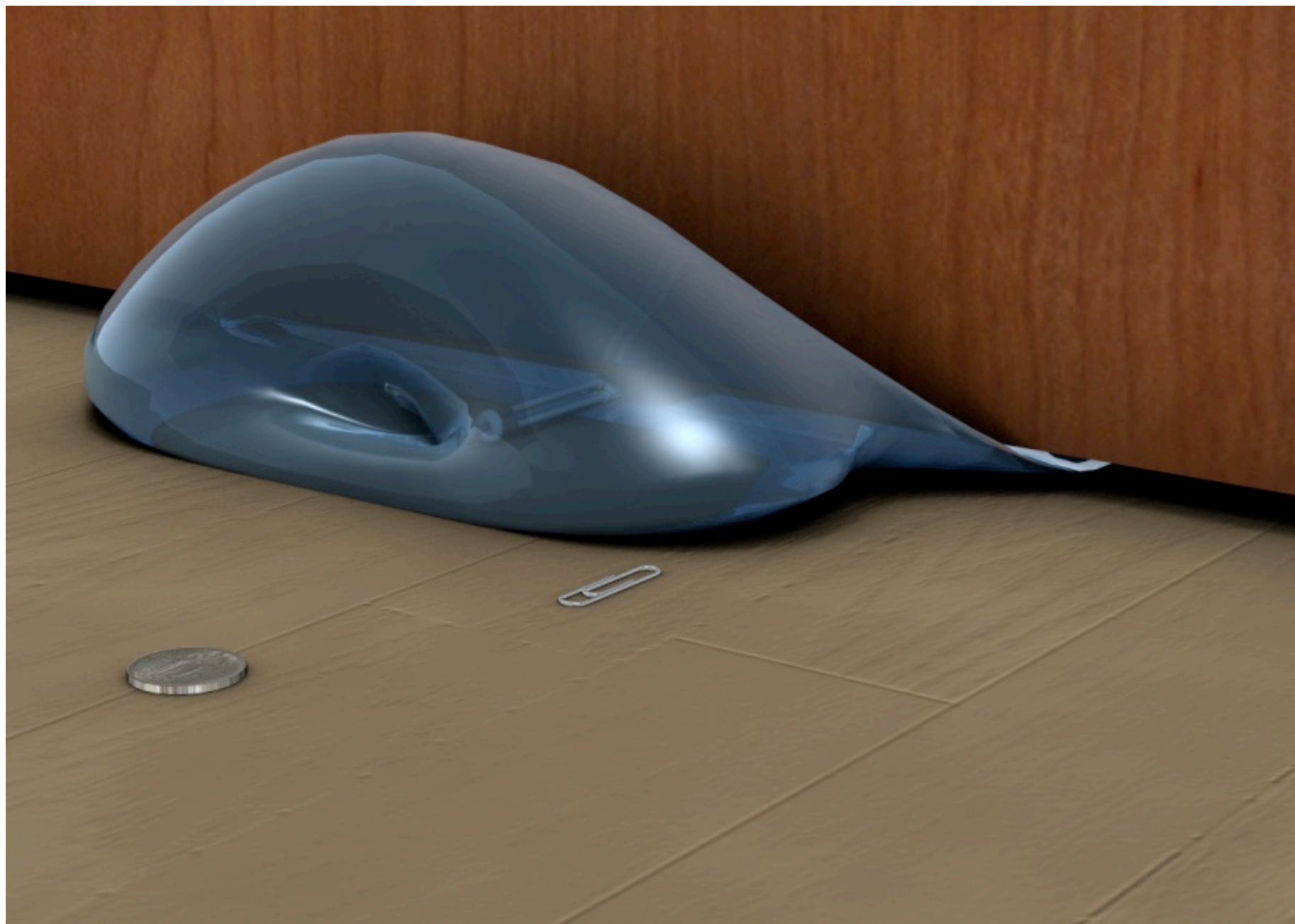


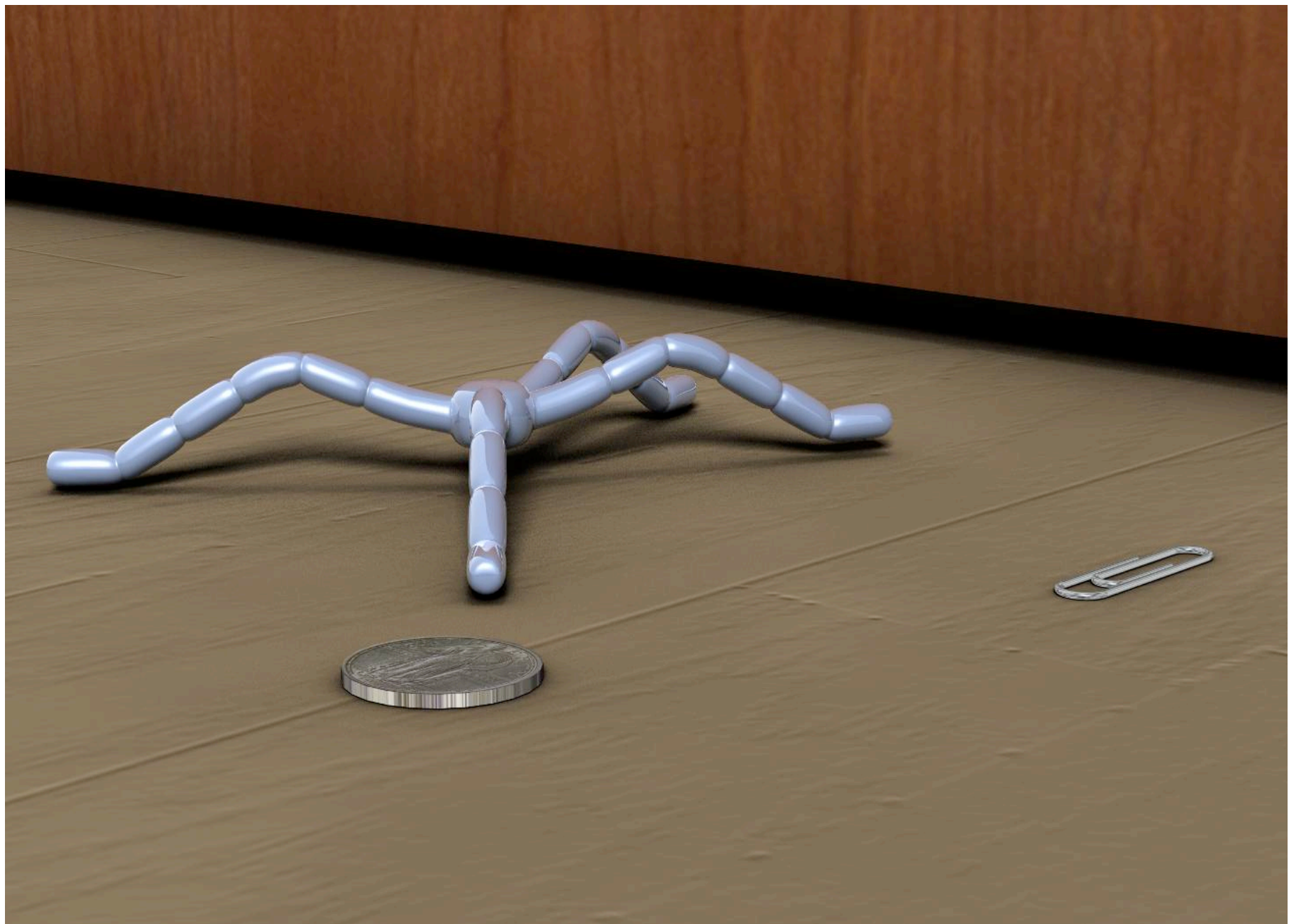
?



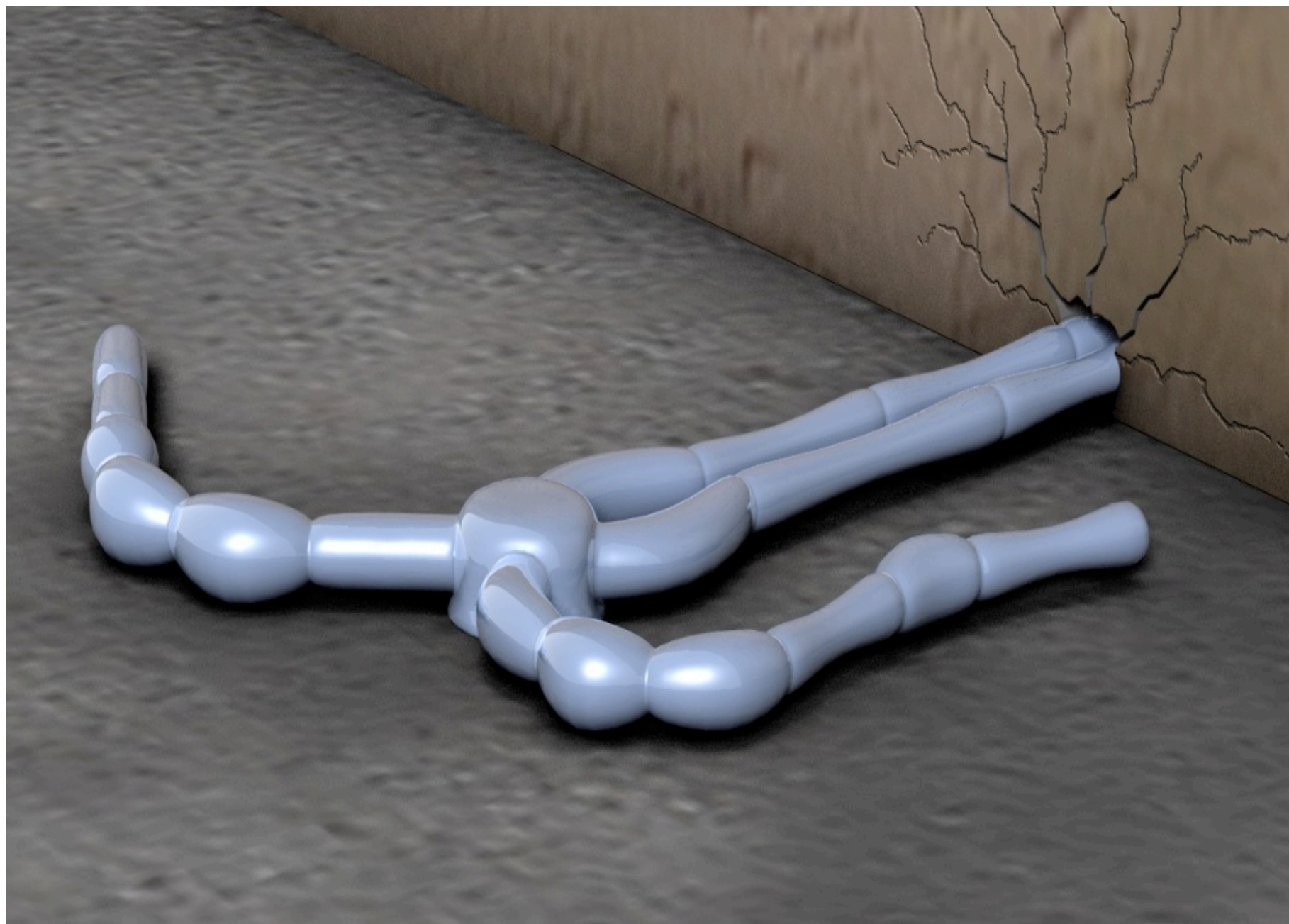












How do you make  
them squirm, squish,  
twist and bend?



YouTube – “Elephant Trunk Up”

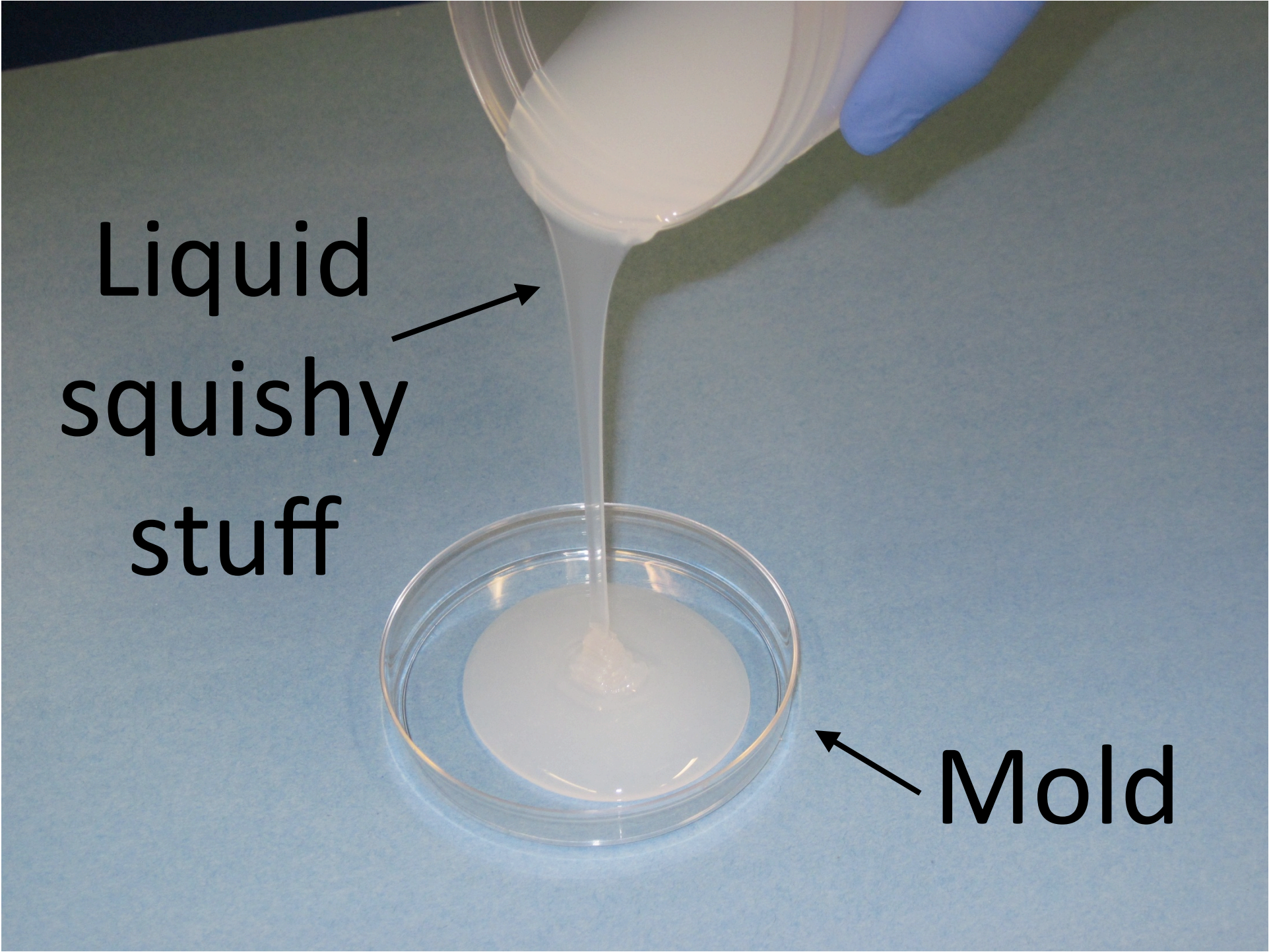




YouTube – “Octopus escaping through a one inch hole”

How do you  
make a robot  
squishy?





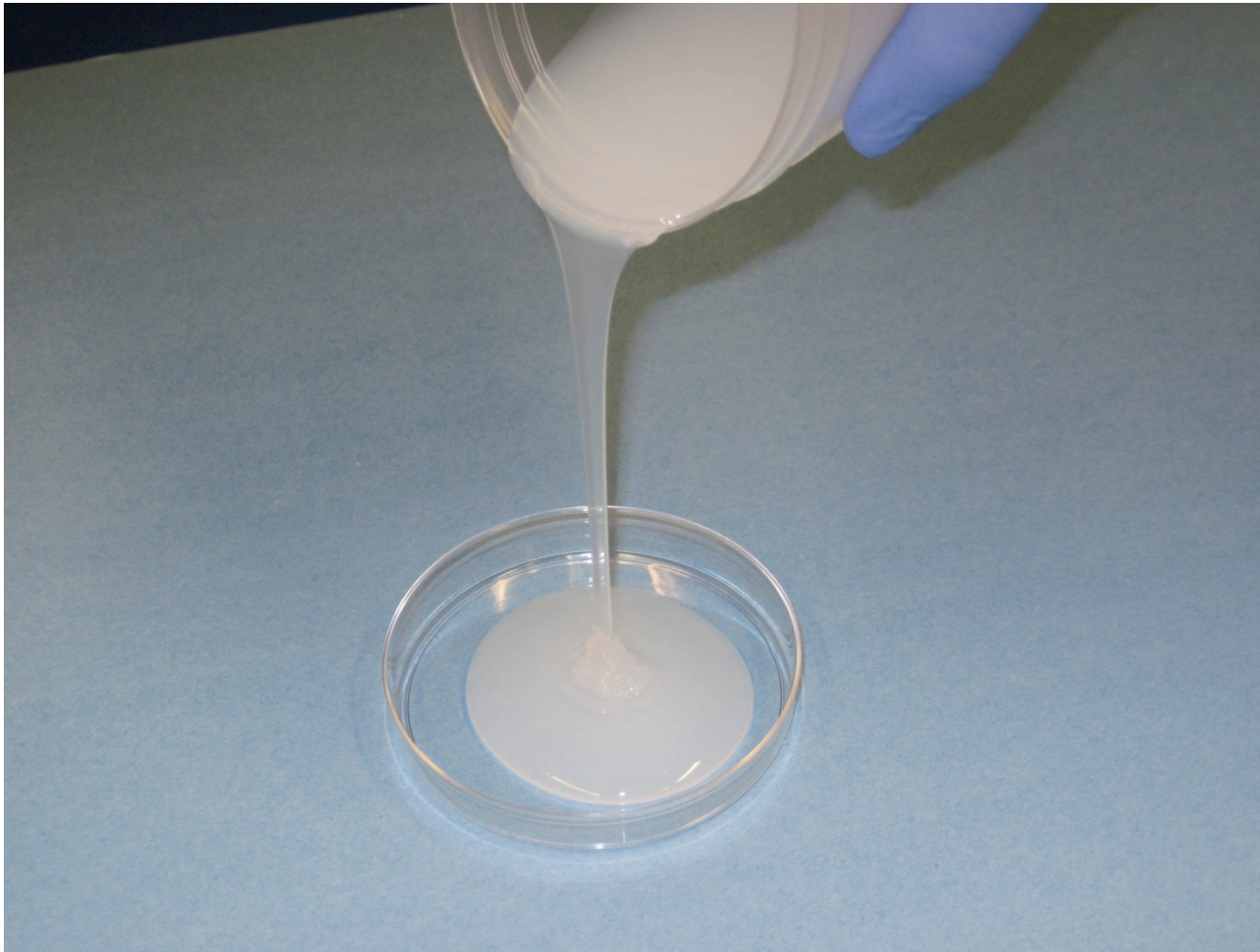
Liquid  
squishy  
stuff

Mold



# What is liquid squishy stuff?

- PDMS (**P**oly**d**imethyl**s**iloxane)
  - EcoFlex<sup>®</sup>
- } Silicon Rubber

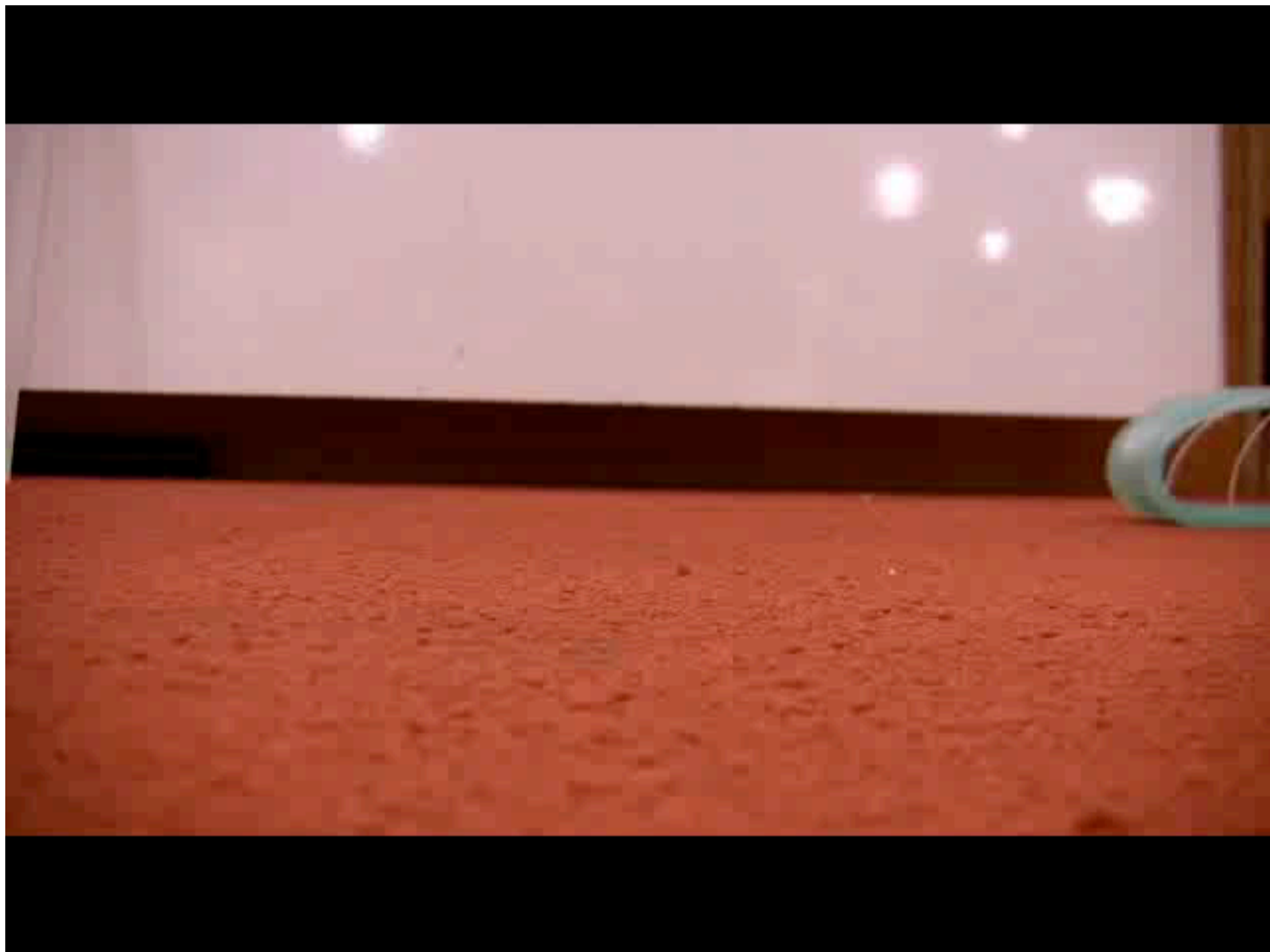


# What is liquid squishy stuff?

EcoFlex<sup>®</sup>







# A different kind of soft robot....

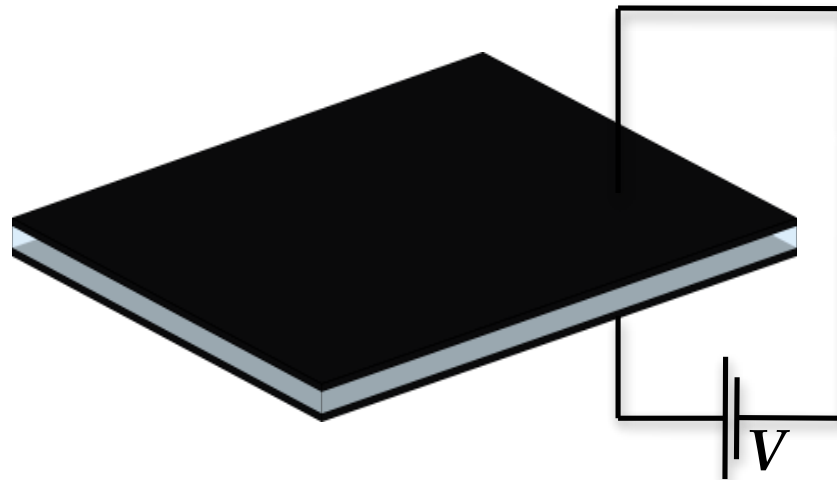
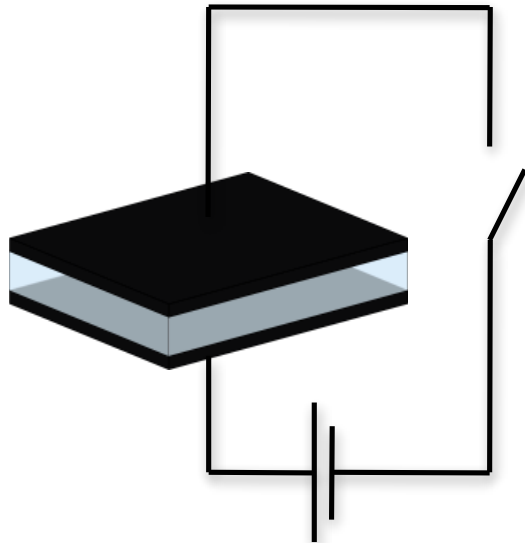
Dielectric elastomer actuator



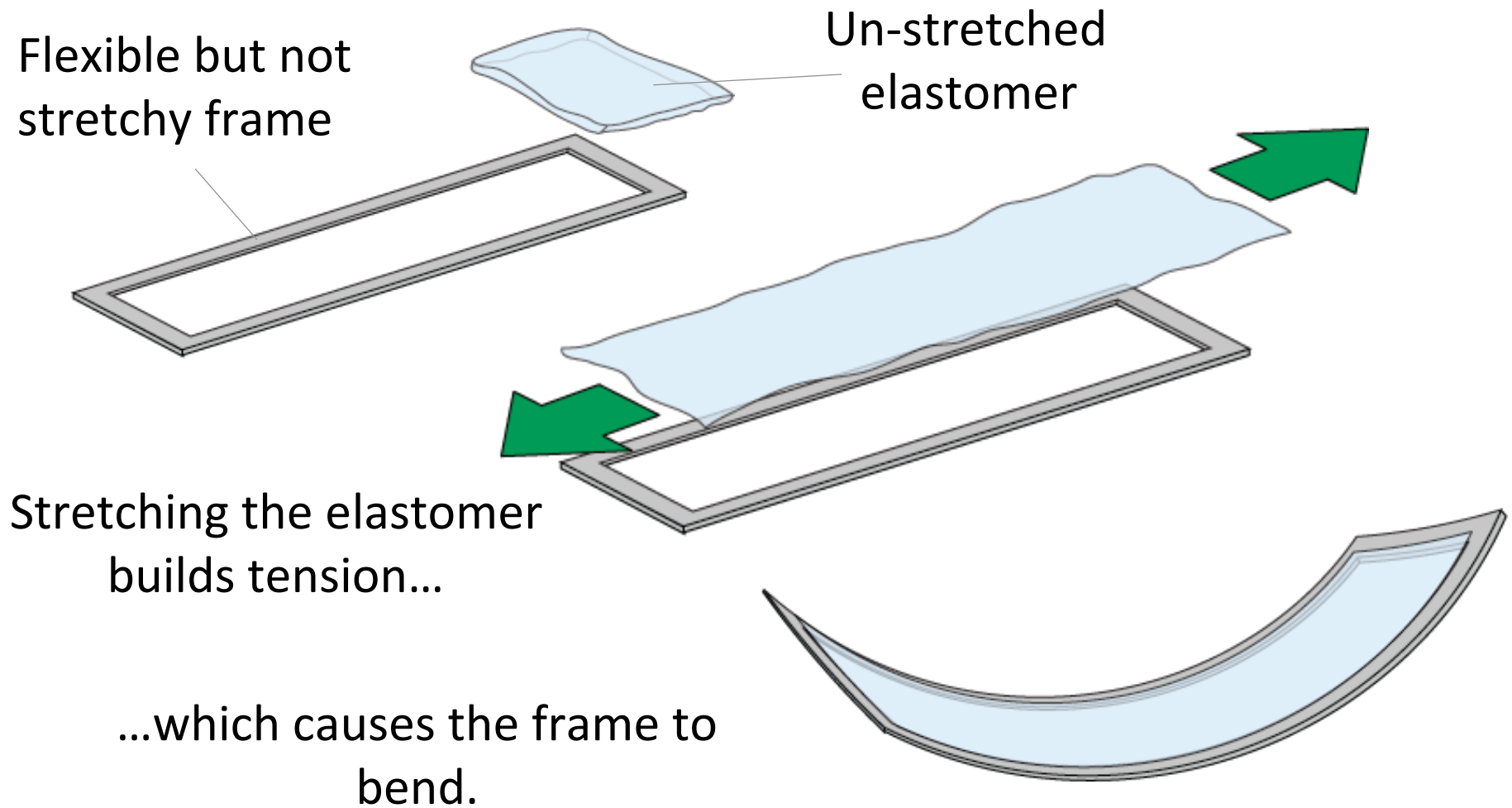
Rubber

Fancy word for “muscle”, or something that moves

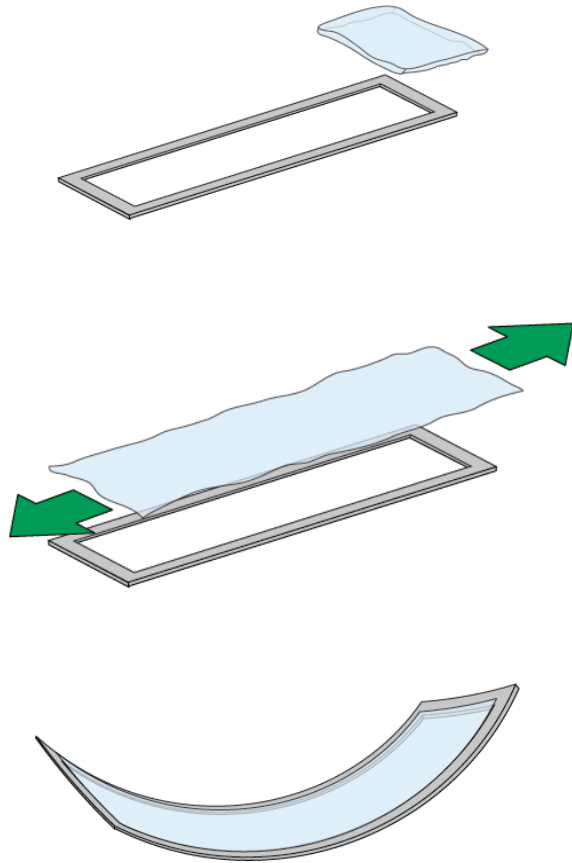
Something that does not conduct



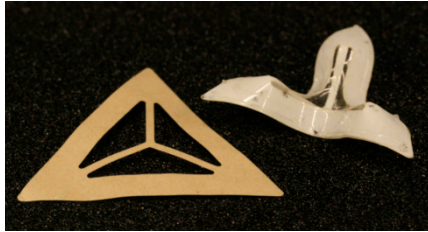
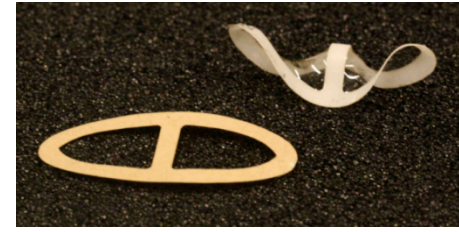
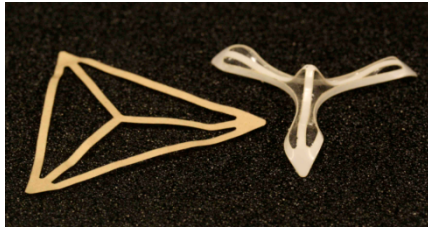
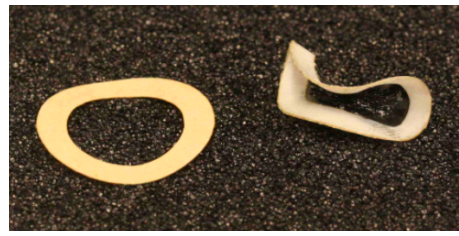
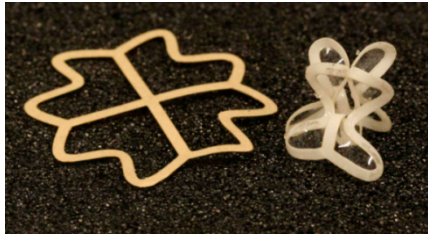
# Can we make 3D shapes from something 2D?



# Can we make 3D shapes from something 2D?

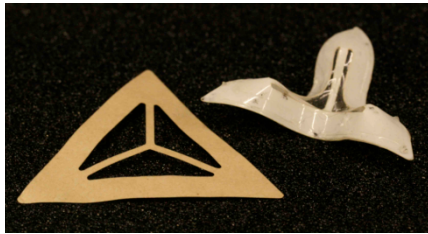
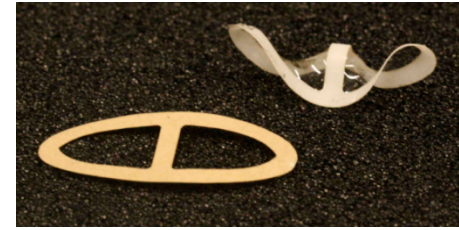
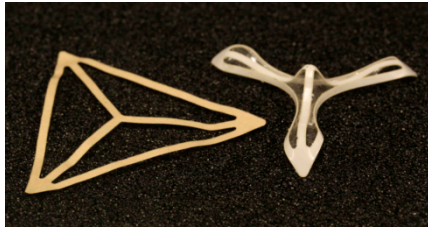
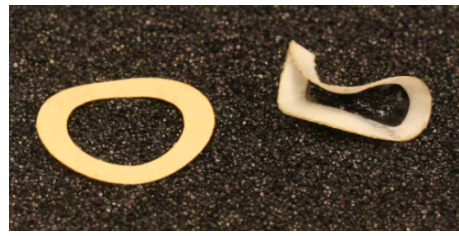
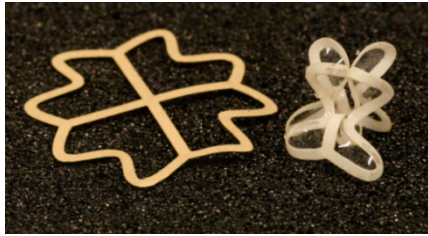


[http://commons.wikimedia.org/wiki/File:Archery\\_competition.jpg](http://commons.wikimedia.org/wiki/File:Archery_competition.jpg)

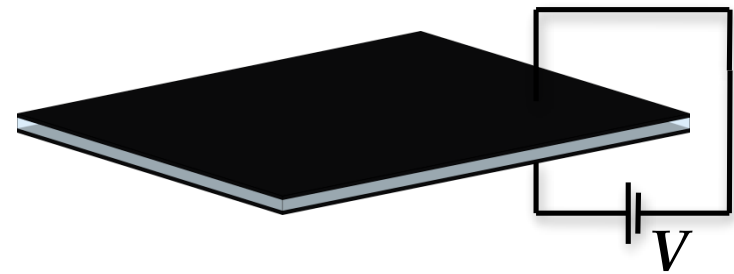
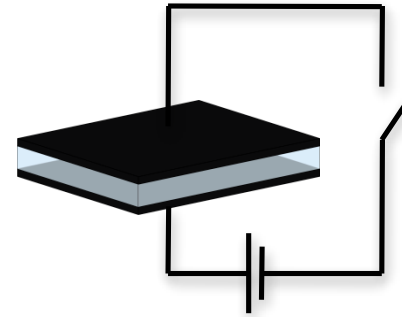


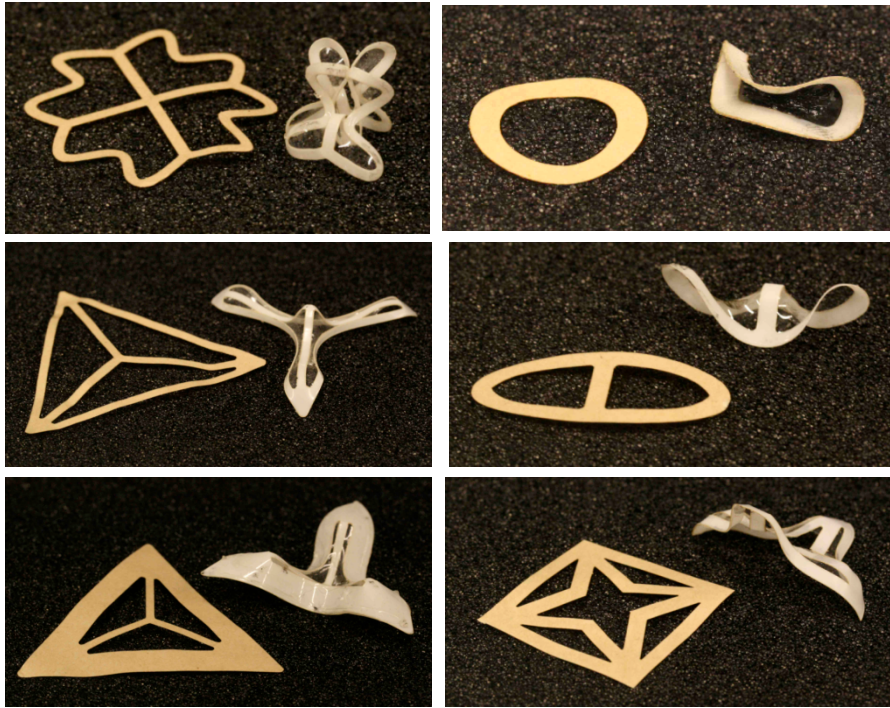
Complex 3D shapes  
from  
simple 2D frames



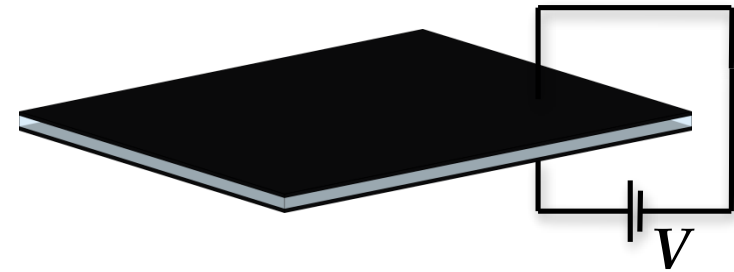
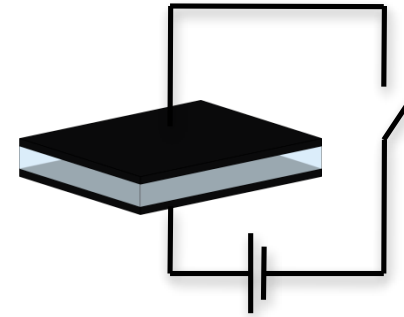


+

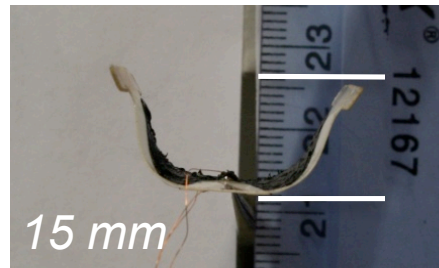




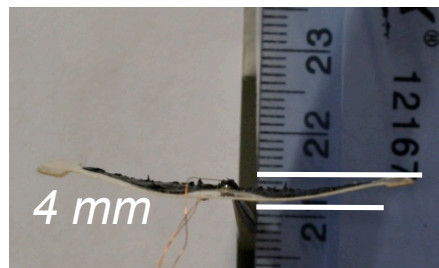
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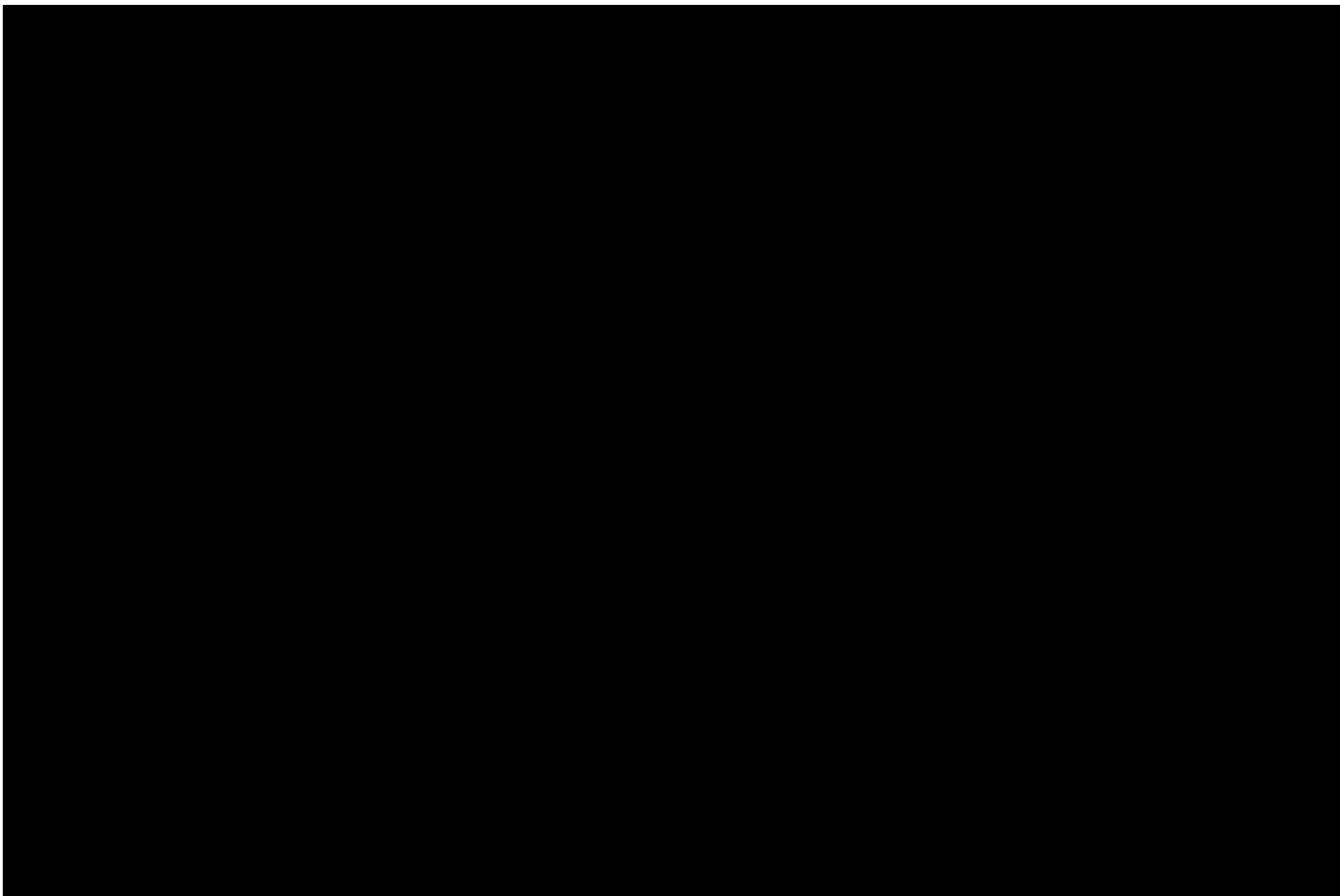


← Rest state  
i.e. no voltage



← Voltage  
applied

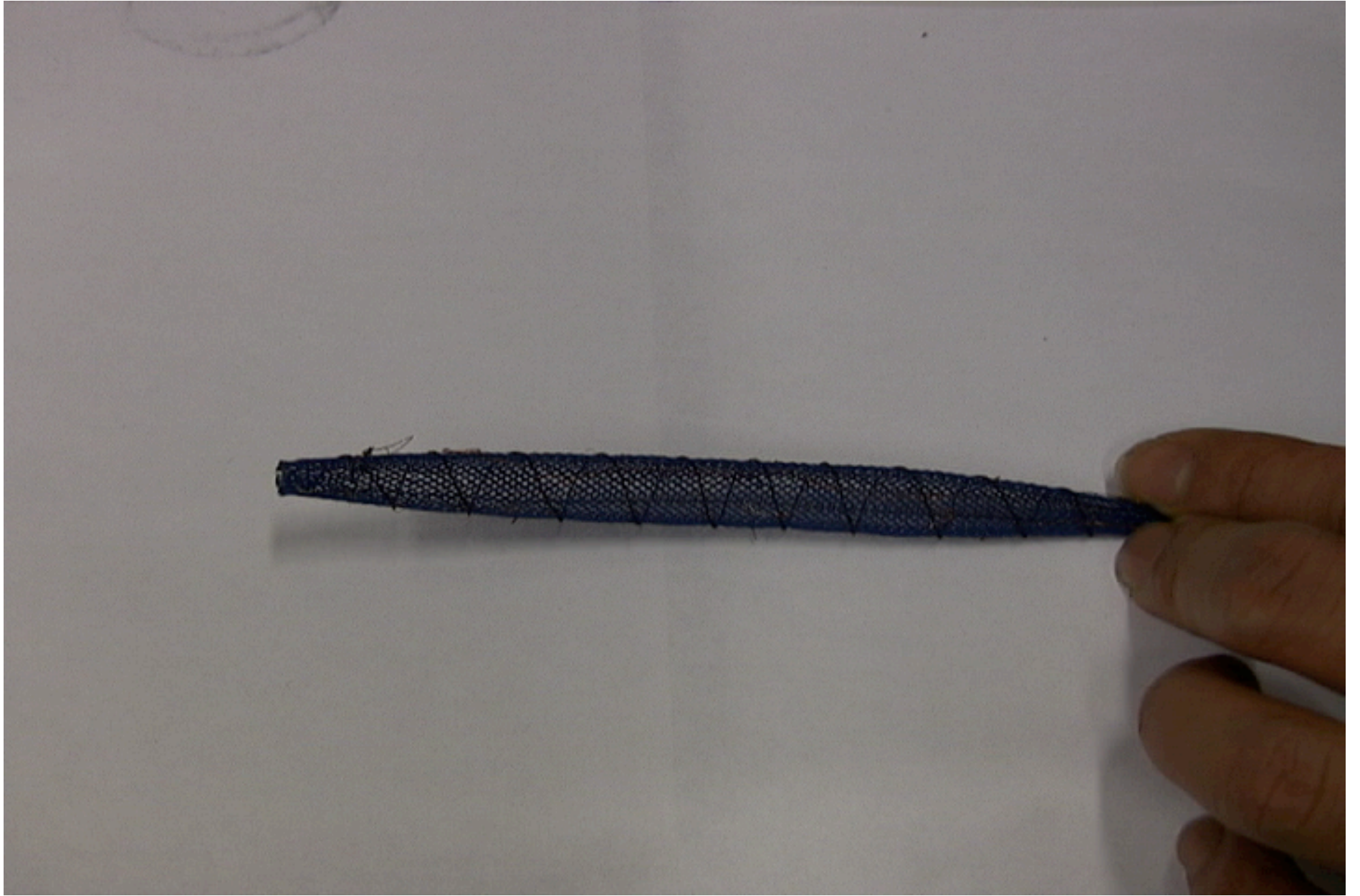
*Electrodes are made  
from conductive  
carbon grease*





# What else is stretchy?

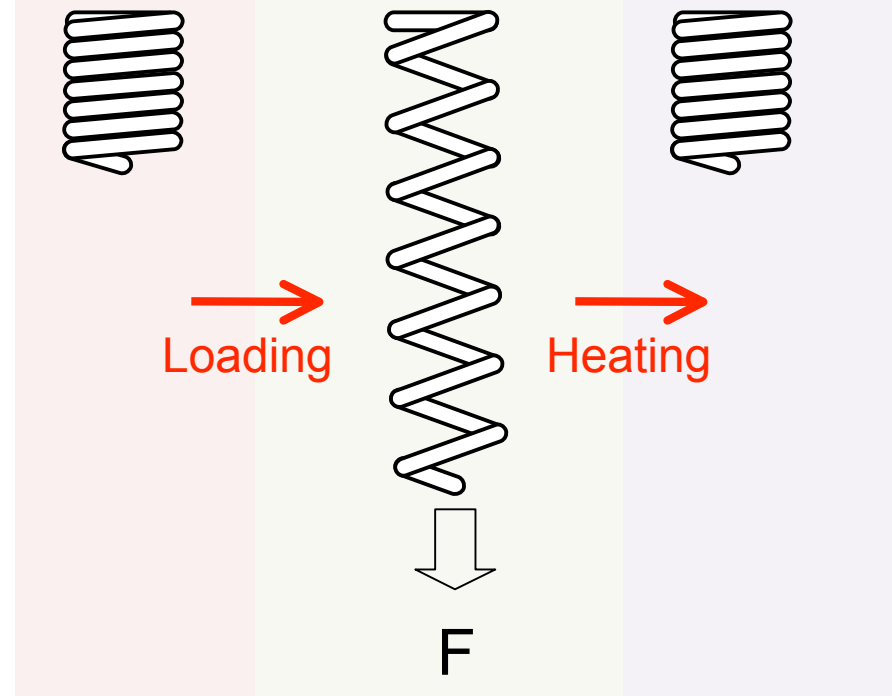
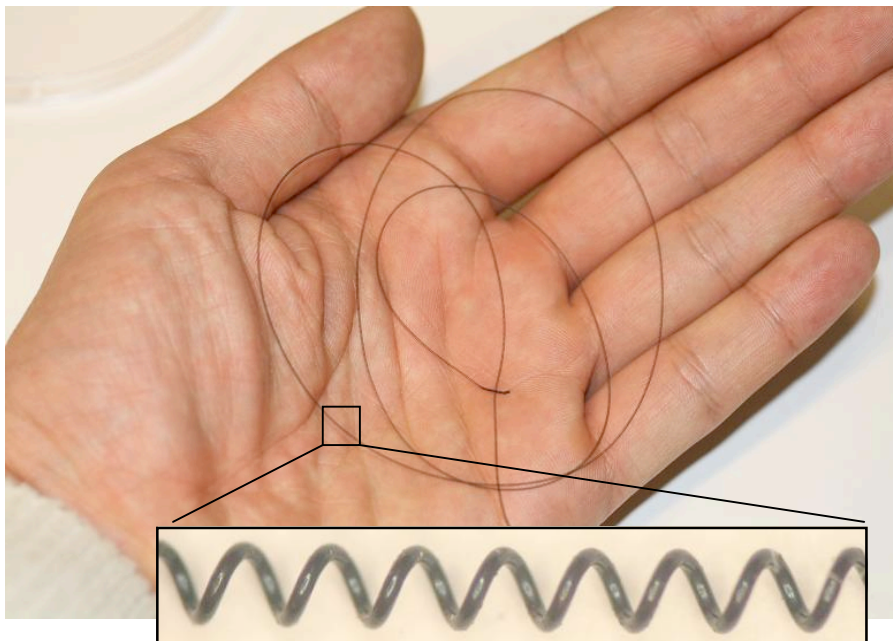
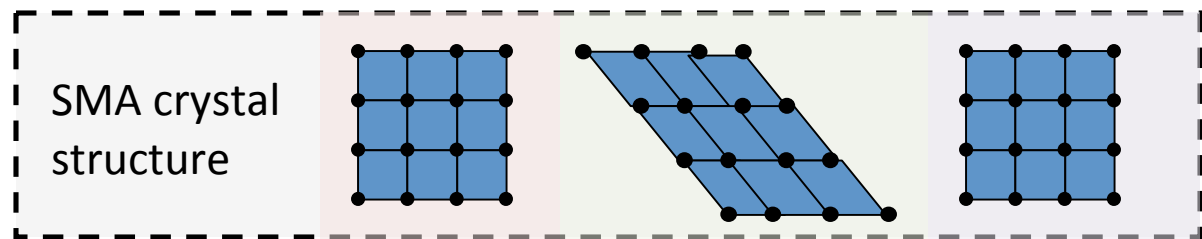






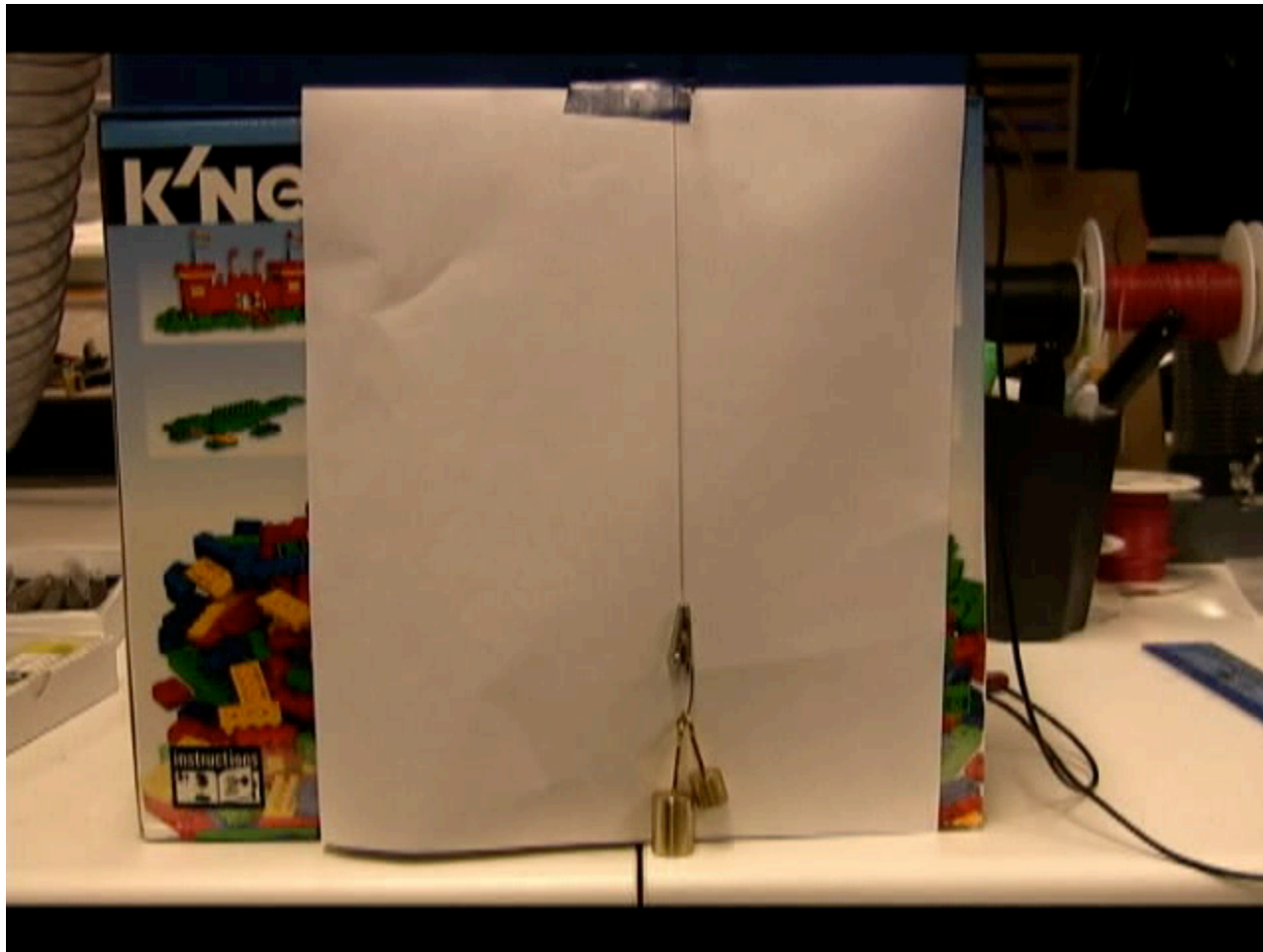
# Meshworm robot

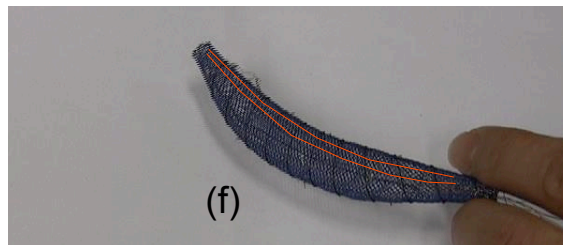
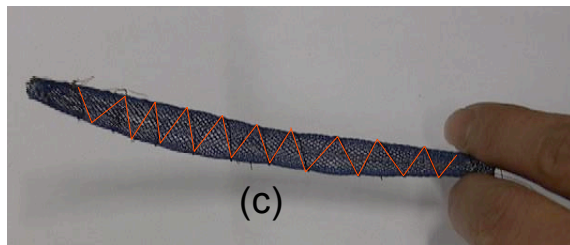
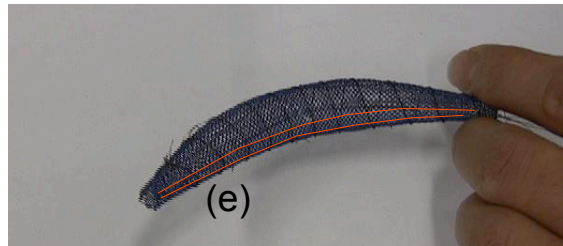
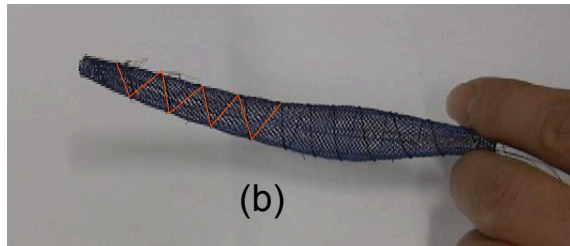
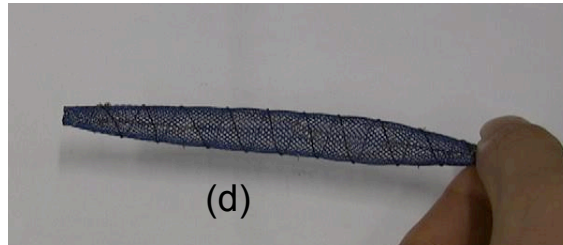
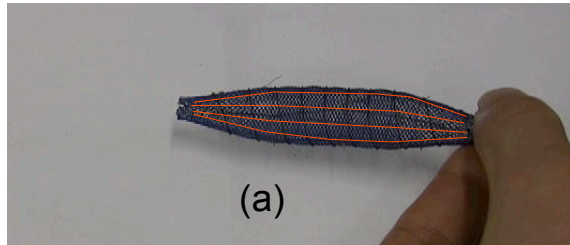
Shape memory alloy (SMA): a metal that “remembers” a certain shape when heat is applied



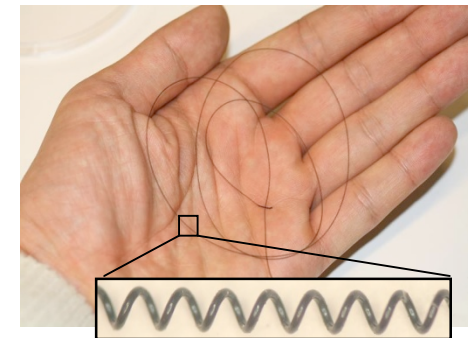
# Meshworm robot

Shape memory alloy (SMA): a metal that “remembers” a certain shape when heat is applied

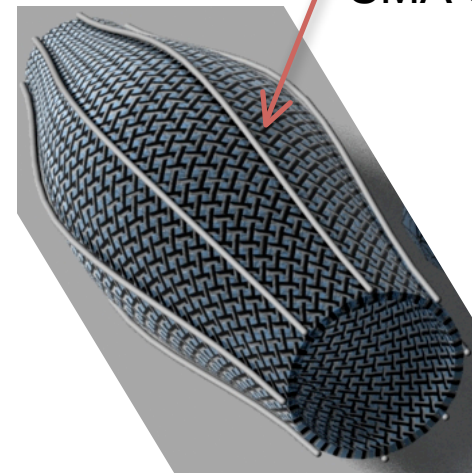




Red means that heat is being applied to that spring



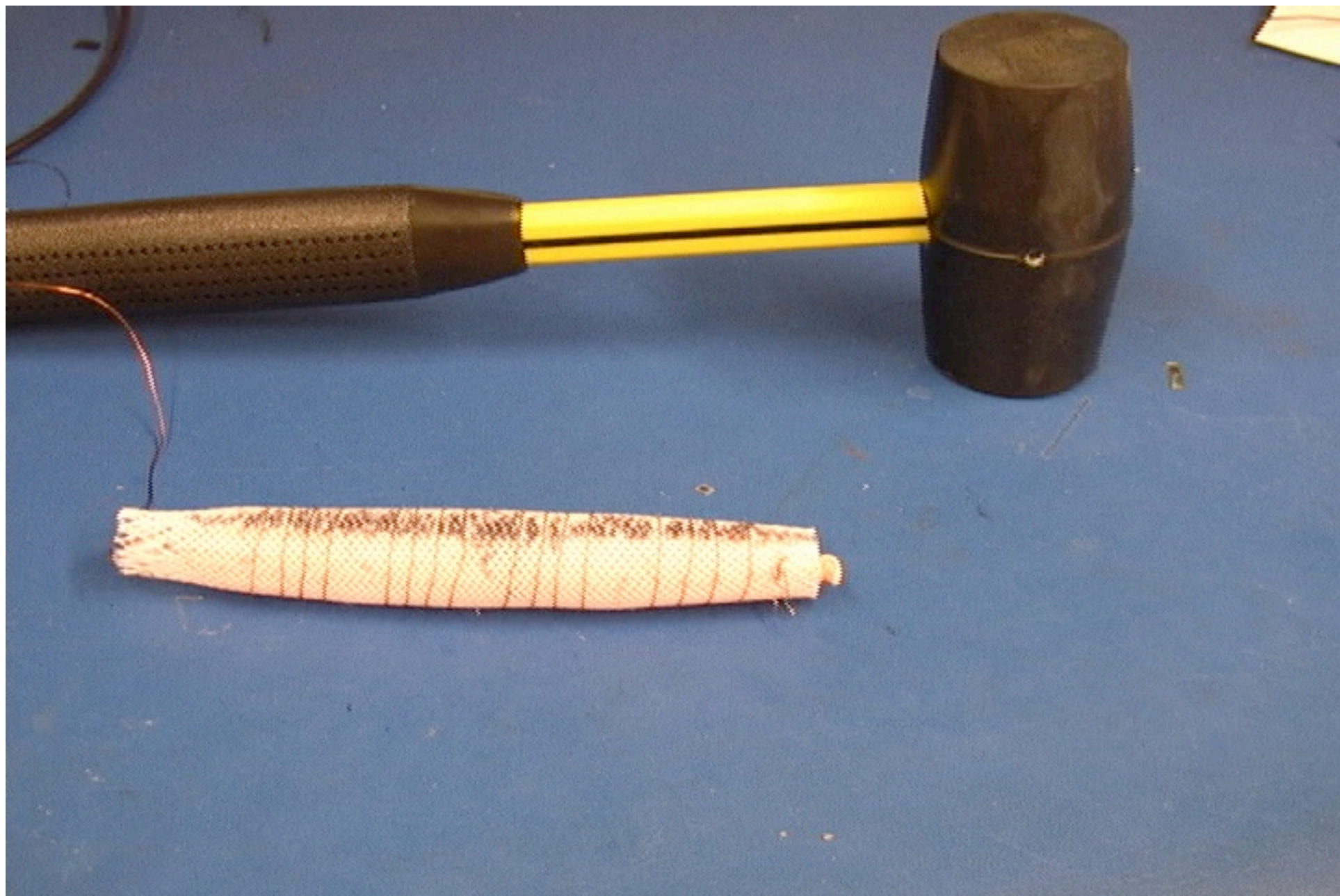
SMA Spring



Locomotion speed :  $0.8\text{cm/sec} = 0.48\text{m/min}$







# Another robot that isn't so squishy....

Can we maintain **stiffness** and still **change shape**?



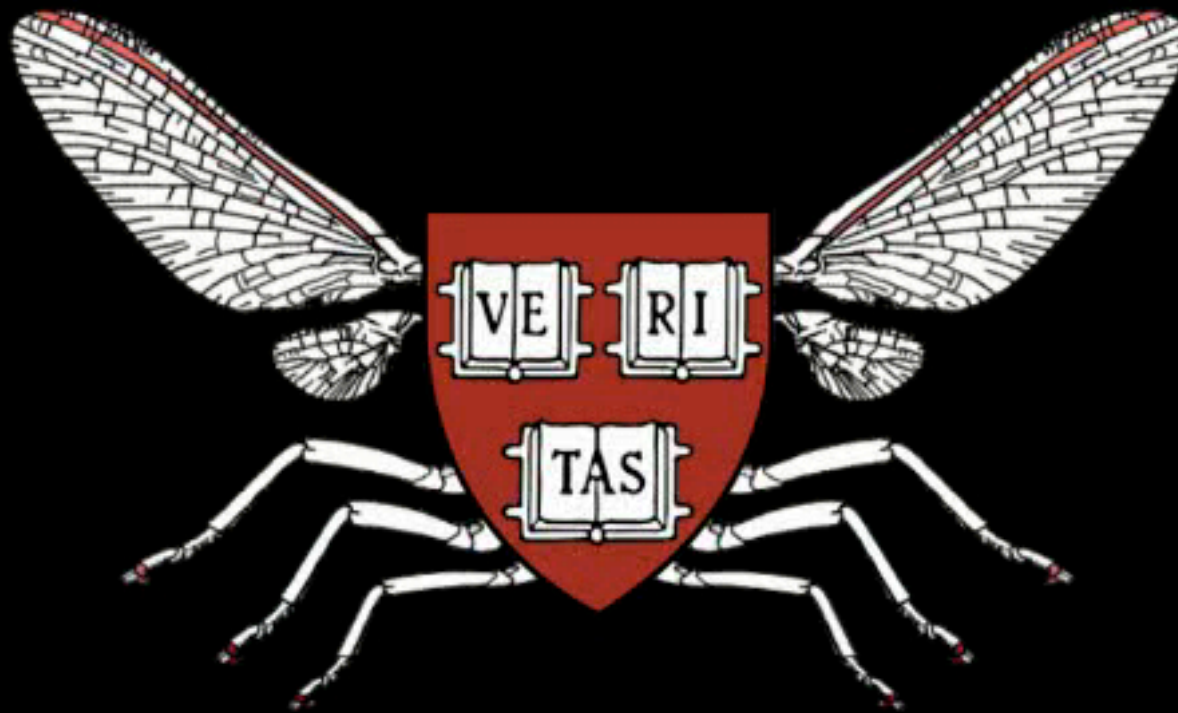
[http://commons.wikimedia.org/wiki/File:Rana\\_Gustavo.jpg](http://commons.wikimedia.org/wiki/File:Rana_Gustavo.jpg)



<http://commons.wikimedia.org/wiki/File:Hipocampo.jpg>



# Programmable Matter by Folding



multiple shapes, compound folds



